



5...4...3...2...1...

SPACE LAUNCH SYSTEM

March 31, 2022

Advances in Launch Vehicle Ascent and Booster Separation CFD

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*Computational Aerosciences Branch
NASA Ames Research Center*



Ascent CFD

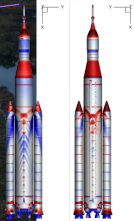


Ascent CFD



Ascent CFD

surface pressure databases

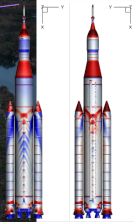


TOP

BOTTOM

Ascent CFD

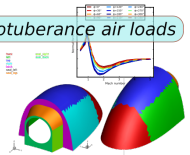
surface pressure databases



TOP

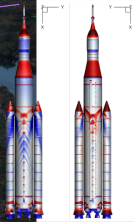
BOTTOM

protuberance air loads



Ascent CFD

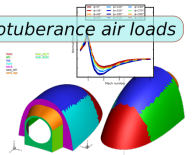
surface pressure databases



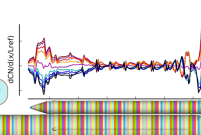
TOP

BOTTOM

protuberance air loads

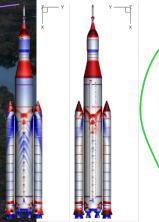


"line" loads

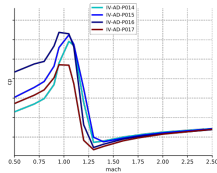


Ascent CFD

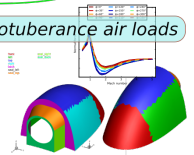
surface pressure databases



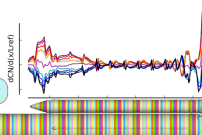
point pressures



protuberance air loads



"line" loads



Ascent CFD

surface pressure databases

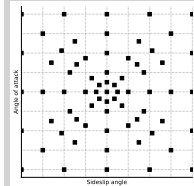
point pressures

protuberance air loads

"line" loads

Run matrix

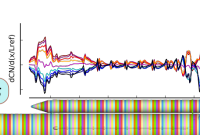
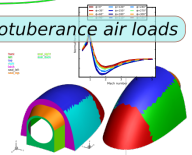
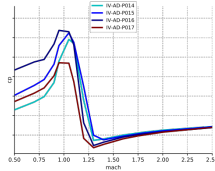
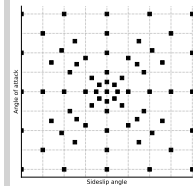
Mach 0.5



Mach 0.7

Mach 0.8

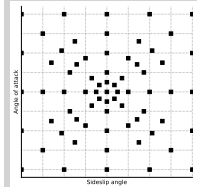
Mach 5.0



Ascent CFD (continued)

Run matrix

Mach 0.5

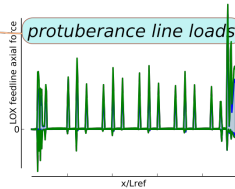
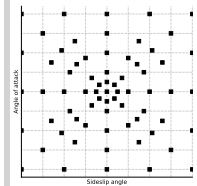


Mach 0.7

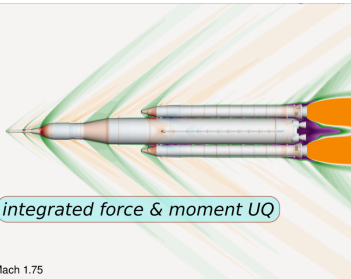
Mach 0.8

⋮

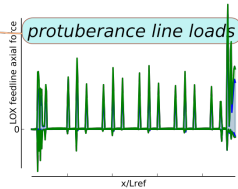
Mach 5.0



Ascent CFD (continued)

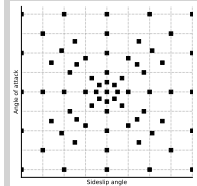


Mach 1.75



Run matrix

Mach 0.5

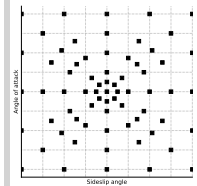


Mach 0.7

Mach 0.8

⋮

Mach 5.0



Do this for 6 (or more) configurations:

Payload to TLI/Moon	> 26 t (57k lbs)	> 26 t (57k lbs)	34–37 t (74k–81k lbs)	37–40 t (81k–88k lbs)	> 45 t (99k lbs)	> 45 t (99k lbs)
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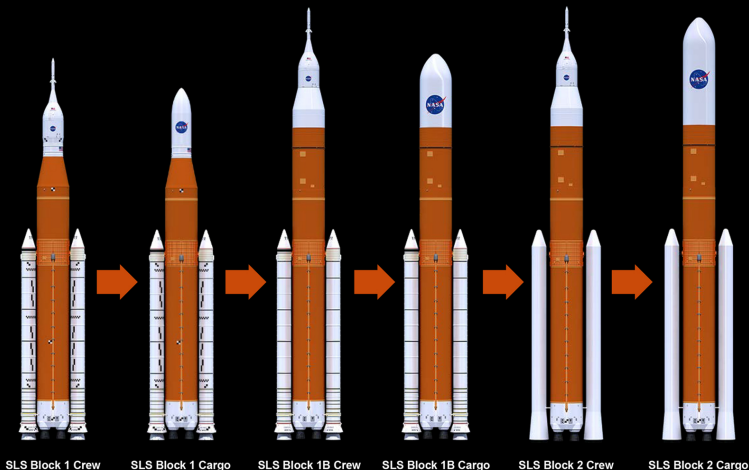
Payload Volume	N/A**	9,030 ft ³ (256m ³)	10,100 ft ³ (286m ³)**	18,970 ft ³ (537 m ³)	10,100 ft ³ (286m ³)**	34,910 ft ³ (988 m ³)
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Trans-Lunar Injection (TLI)

is a propulsive maneuver used to set a spacecraft on a trajectory that will cause it to arrive at the Moon. A spacecraft performs **TLI** to begin a lunar transfer from a low circular parking orbit around Earth.

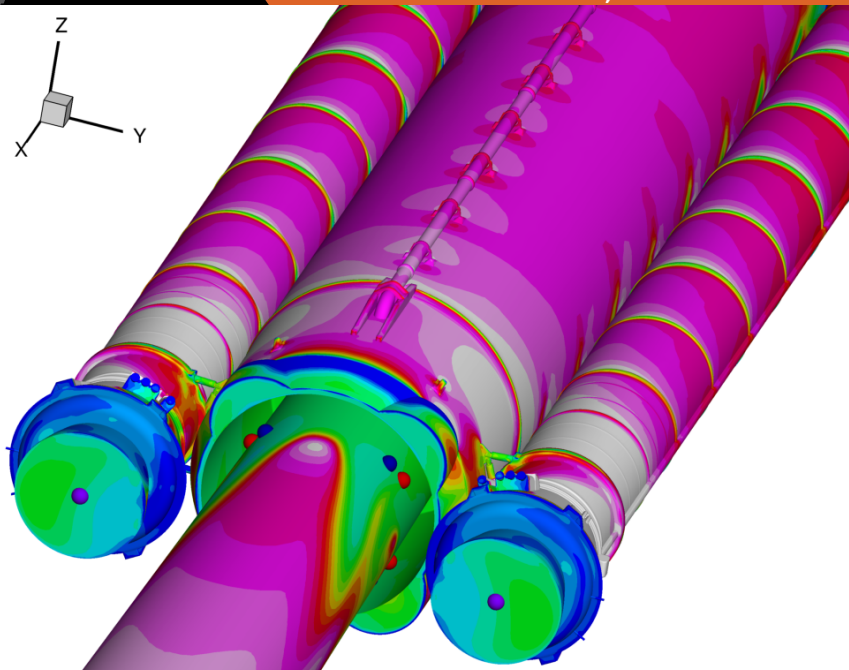
The numbers depicted here indicate the mass capability at the Trans-Lunar Injection point.

** Not including Orion/Service Module volume



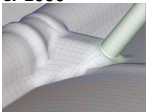
Maximum Thrust	8.8M lbs	8.8M lbs	8.8M lbs	8.8M lbs	11.9M lbs	11.9M lbs
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Run CFD on wind tunnel models, too

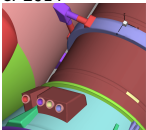


History, from Space Shuttle to 2022

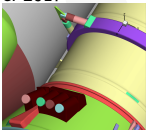
Space Shuttle,
c. 2006



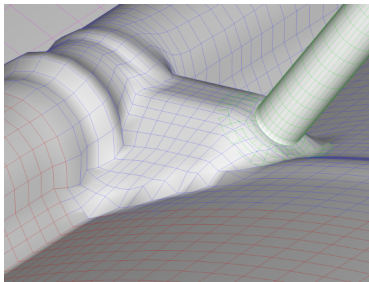
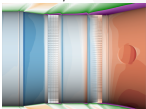
Artemis I DAC3,
c. 2014



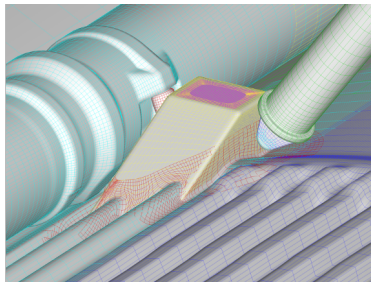
Artemis I VAC1,
c. 2017



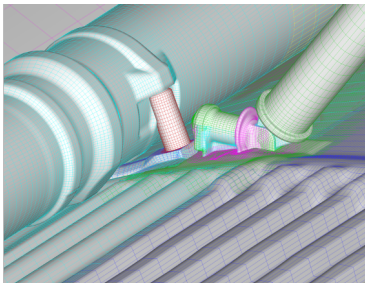
Artemis I
FRAC1, c. 2022



1990s



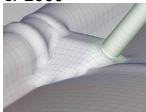
c. 2003



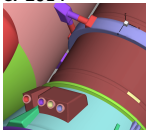
c. 2006

History, from Space Shuttle to 2022

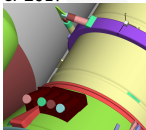
Space Shuttle,
c. 2006



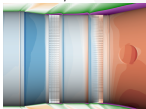
Artemis I DAC3,
c. 2014



Artemis I VAC1,
c. 2017



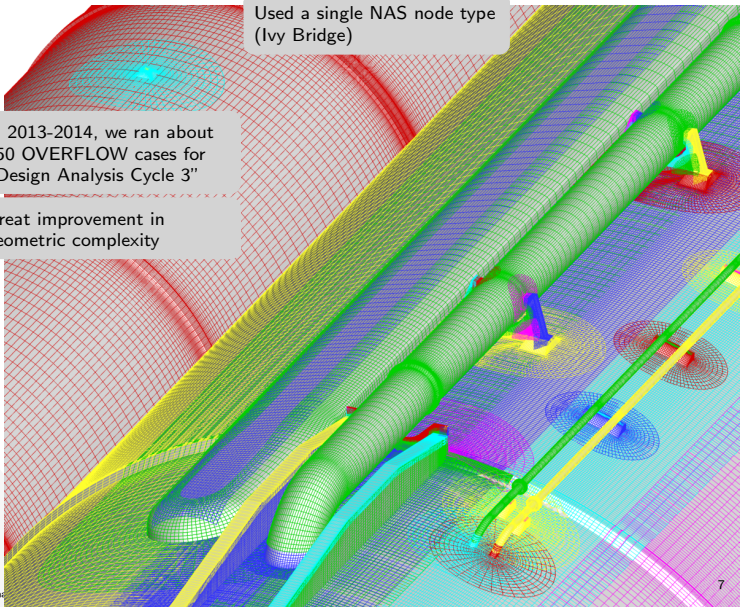
Artemis I
FRAC1, c. 2022



Used a single NAS node type
(Ivy Bridge)

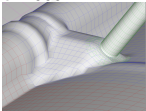
In 2013-2014, we ran about
850 OVERFLOW cases for
"Design Analysis Cycle 3"

Great improvement in
geometric complexity

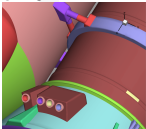


History, from Space Shuttle to 2022

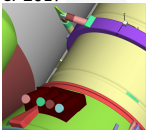
Space Shuttle,
c. 2006



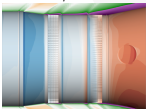
Artemis I DAC3,
c. 2014



Artemis I VAC1,
c. 2017

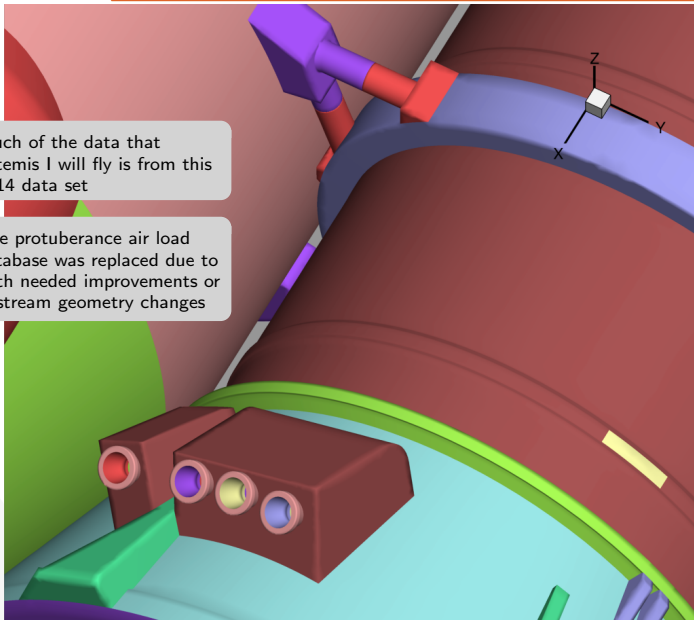


Artemis I
FRAC1, c. 2022



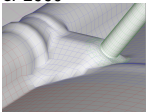
Much of the data that Artemis I will fly is from this 2014 data set

The protuberance air load database was replaced due to both needed improvements or upstream geometry changes

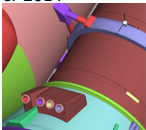


History, from Space Shuttle to 2022

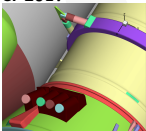
Space Shuttle,
c. 2006



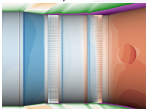
Artemis I DAC3,
c. 2014



Artemis I VAC1,
c. 2017

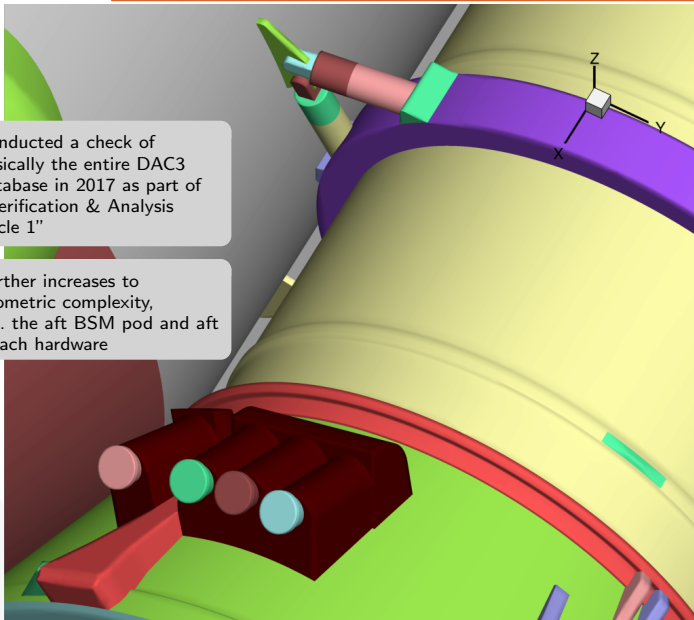


Artemis I
FRAC1, c. 2022



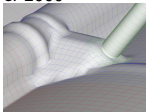
Conducted a check of basically the entire DAC3 database in 2017 as part of "Verification & Analysis Cycle 1"

Further increases to geometric complexity, e.g. the aft BSM pod and aft attach hardware

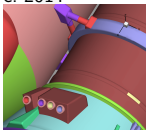


History, from Space Shuttle to 2022

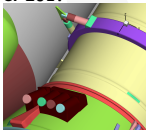
Space Shuttle,
c. 2006



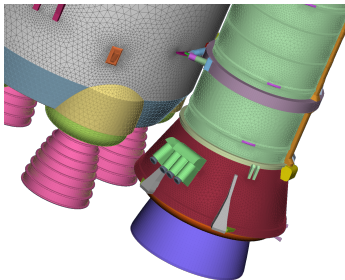
Artemis I DAC3,
c. 2014



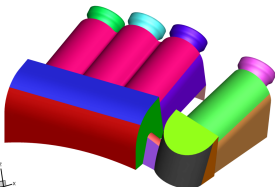
Artemis I VAC1,
c. 2017



Artemis I
FRAC1, c. 2022

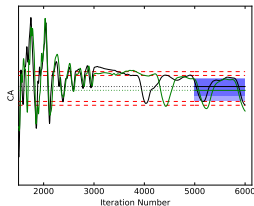


3PodFairing_front
3PodFairing_left
3PodFairing_right
3PodFairing_top
3Pod_left
3PodFairing_back
1PodFairing_front
1PodFairing_left
1PodFairing_top
1PodFairing_right
1PodFairing_back
3Pod_left
3Pod_top
3Pod_right
3Pod_back
1Pod_left
1Pod_top
1Pod_right
1Pod_back
Bridge_front
Bridge_top
Bridge_back
Noz1
Noz2
Noz4

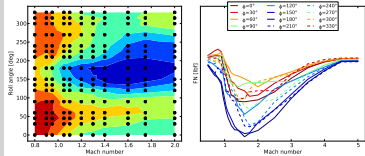


www.nasa.gov/sls

Created the CAPE software package to improve flexibility, speed, and reproducibility
We were able to run 1300 cases in both FUN3D and OVERFLOW



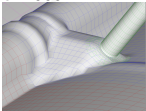
Instrument and check iterative convergence while running



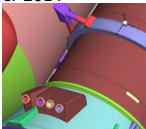
Attempt to make meaningful plots

History, from Space Shuttle to 2022

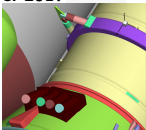
Space Shuttle,
c. 2006



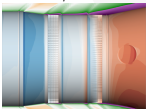
Artemis I DAC3,
c. 2014



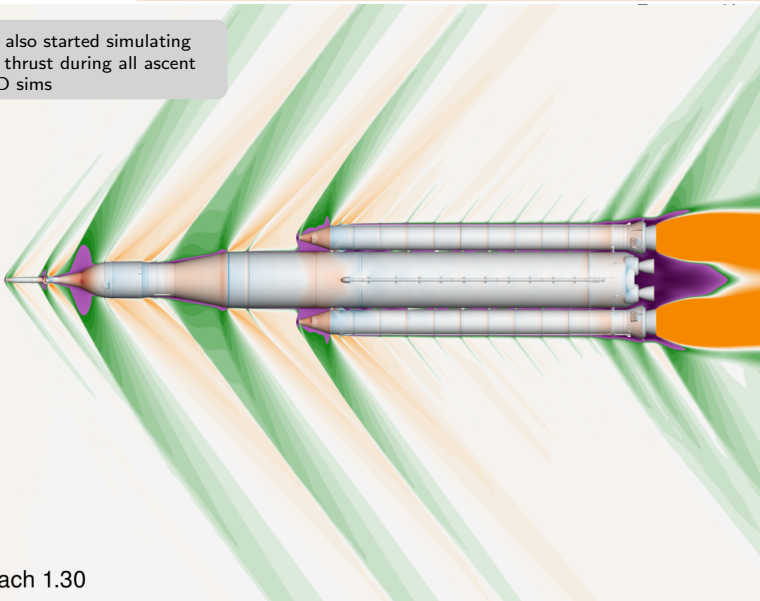
Artemis I VAC1,
c. 2017



Artemis I
FRAC1, c. 2022

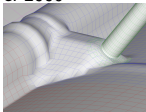


We also started simulating
the thrust during all ascent
CFD sims

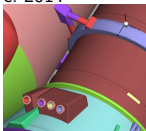


History, from Space Shuttle to 2022

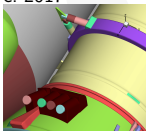
Space Shuttle,
c. 2006



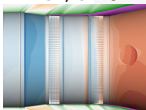
Artemis I DAC3,
c. 2014



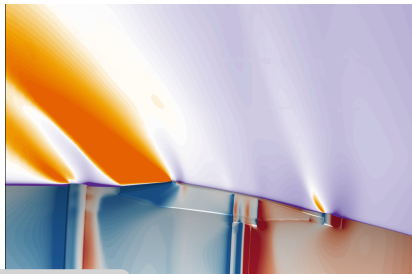
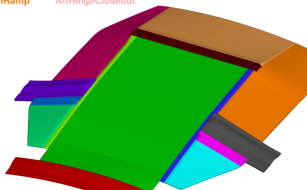
Artemis I VAC1,
c. 2017



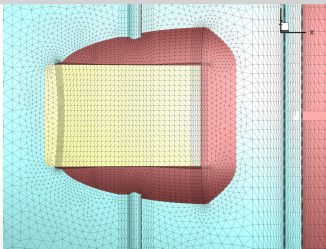
Artemis I
FRAC1, c. 2022



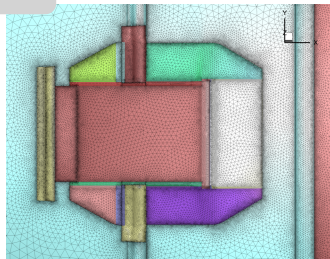
FwdEdgeSeal
OMLAccessPanel
LeftBulbSeal
LeftFwdSealRamp
LeftSealMountingCover
LeftRampSeal
LeftAftSealRamp
RightBulbSeal
RightFwdSealRamp
RightSealMountingCover
RightRampSeal
RightAftSealRamp
AftRamp
SealFlange
AftHingeCloseout



Lots of late-breaking questions. This example is the umbilical that connects the crew module to the service module, which changed a great deal

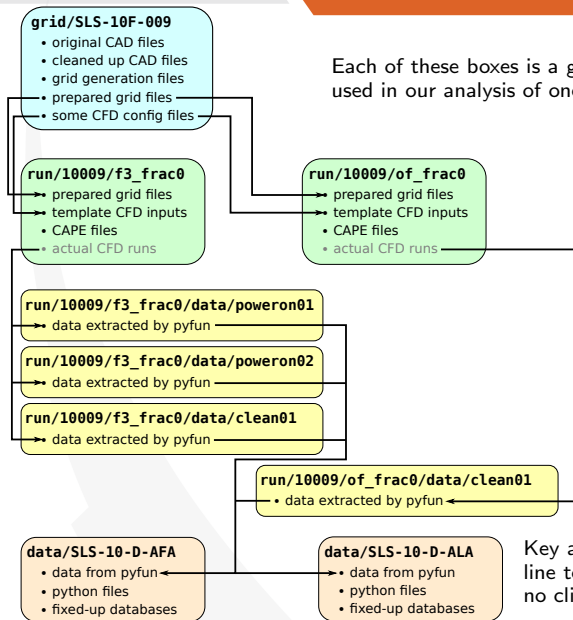


SLS-10008 CSM umbilical mesh



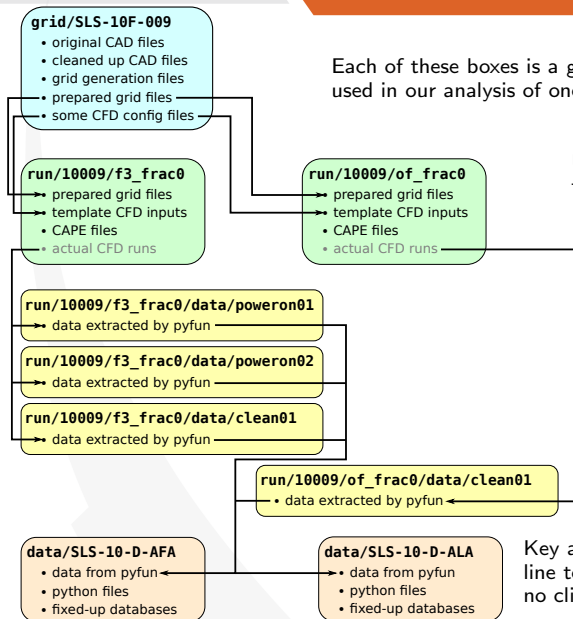
2020 geometry

Tool #1: treat CFD like software dev



Key aspect: use code and/or command line to generate inputs for each CFD case; no clicking to copy files manually!

Tool #1: treat CFD like software dev



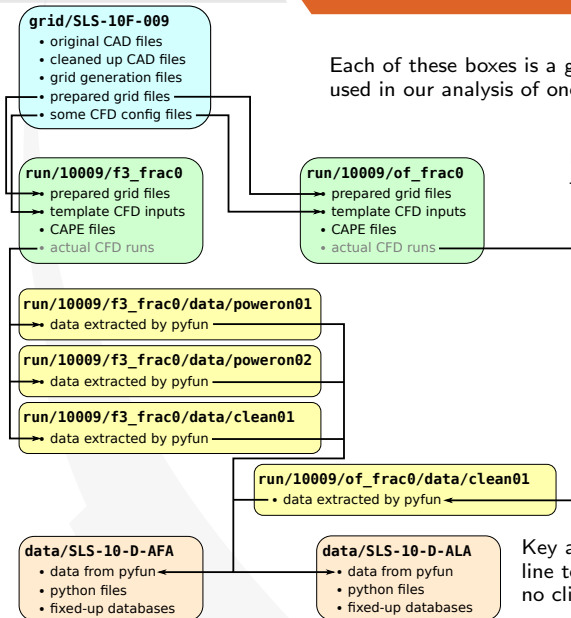
Each of these boxes is a git repository used in our analysis of one Artemis I task

Using version control software like this has certain implications:

- No spreadsheets, rich-text word docs, etc.
- Everything that changes w/ time should be text
- Can be a challenge for new team members to learn

Key aspect: use code and/or command line to generate inputs for each CFD case; no clicking to copy files manually!

Tool #1: treat CFD like software dev



Each of these boxes is a git repository used in our analysis of one Artemis I task

Using version control software like this has certain implications:

- No spreadsheets, rich-text word docs, etc.
- Everything that changes w/ time should be text
- Can be a challenge for new team members to learn
- Avoid having one HUGE repo where all the work is done
- This requires some planning

Key aspect: use code and/or command line to generate inputs for each CFD case; no clicking to copy files manually!

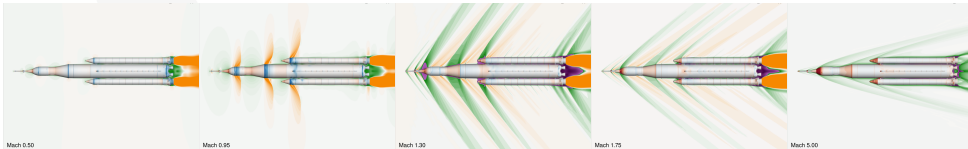
Tool #2: CAPE

Use a single tool to set up, run, backup, and extract data from each case

Running

Example: set up and submit 10 OVERFLOW jobs at Mach 1.75

```
$ pyover --re m1.75 -n 10
```



Tool #2: CAPE

Use a single tool to set up, run, backup, and extract data from each case

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```
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```

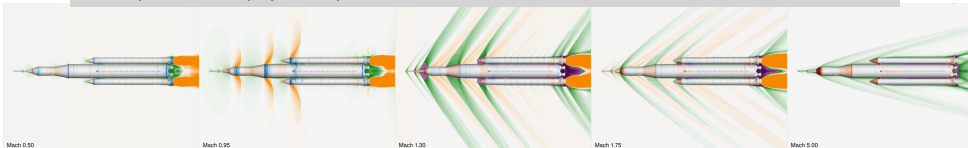
Checking status

Example: Check status of FUN3D jobs at Mach 1.75

```
$ pyfun --re m1.75 -c
```

Case	Config/Run Directory	Status	Iterations	Que	CPU Time
81	poweron/m1.75a0.0r000.0	RUNNING	4237/5000	R	11273.7
82	poweron/m1.75a4.0r000.0	QUEUE	3000/4000	Q	2633.1
83	poweron/m1.75a4.0r090.0	PASS	5000/5000	.	10743.3

PASS=1, RUNNING=1, QUEUE=1,



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Running

Example: set up and submit 10 OVERFLOW jobs at Mach 1.75

```
$ pyover --re m1.75 -n 10
```

Generate report

Example: generate \LaTeX report for cases 79 and 402

```
$ pycart -I 79,402 --report
```

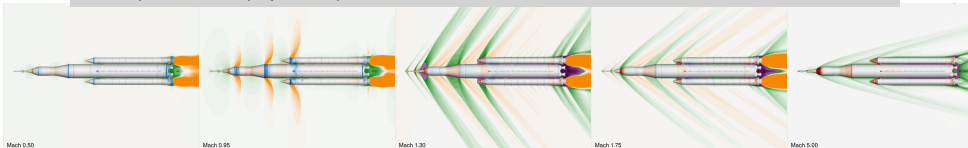
Checking status

Example: Check status of FUN3D jobs at Mach 1.75

```
$ pyfun --re m1.75 -c
```

Case	Config/Run Directory	Status	Iterations	Que	CPU Time
81	poweron/m1.75a0.0r000.0	RUNNING	4237/5000	R	11273.7
82	poweron/m1.75a4.0r000.0	QUEUE	3000/4000	Q	2633.1
83	poweron/m1.75a4.0r090.0	PASS	5000/5000	.	10743.3

PASS=1, RUNNING=1, QUEUE=1,



Tool #2: CAPE

Use a single tool to set up, run, backup, and extract data from each case

Running

Example: set up and submit 10 OVERFLOW jobs at Mach 1.75

```
$ pyover --re m1.75 -n 10
```

Generate report

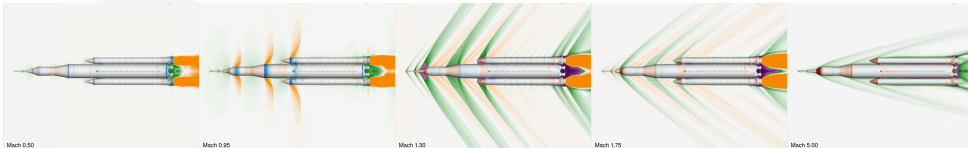
Example: generate \LaTeX report for cases 79 and 402

```
$ pycart -I 79,402 --report
```

Collect forces and moments

Example: update F&M database for negative-sideslip cases

```
$ pyfun --cons "beta<0" --fm
```



Tool #2: CAPE

Use a single tool to set up, run, backup, and extract data from each case

Running

Example: set up and submit 10 OVERFLOW jobs at Mach 1.75

```
$ pyover --re m1.75 -n 10
```

Generate report

Example: generate \LaTeX report for cases 79 and 402

```
$ pycart -I 79,402 --report
```

Collect forces and moments

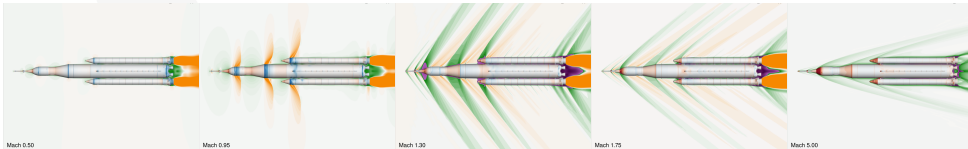
Example: update F&M database for negative-sideslip cases

```
$ pyfun --cons "beta<0" --fm
```

Extract protuberance air loads

Example: get patch loads for components starting with "M"

```
$ pyover --triqfm "M*"
```



Tool #2: CAPE

Use a single tool to set up, run, backup, and extract data from each case

Running

Example: set up and submit 10 OVERFLOW jobs at Mach 1.75

```
$ pyover --re m1.75 -n 10
```

Generate report

Example: generate \LaTeX report for cases 79 and 402

```
$ pycart -I 79,402 --report
```

Collect forces and moments

Example: update F&M database for negative-sideslip cases

```
$ pyfun --cons "beta<0" --fm
```

Extract protuberance air loads

Example: get patch loads for components starting with "M"

```
$ pyover --triqfm "M*"
```

Archiving

Example: create backup and delete large files from working copy

```
$ pyover --archive
```

...and recover

Example: retrieve case 309 from archive for more analysis

```
$ pyover --unarchive -I 309
```

Tool #3: robust CFD solvers



FUN3D

Fully Unstructured Navier-Stokes

<https://fun3d.larc.nasa.gov>

OVERFLOW 2

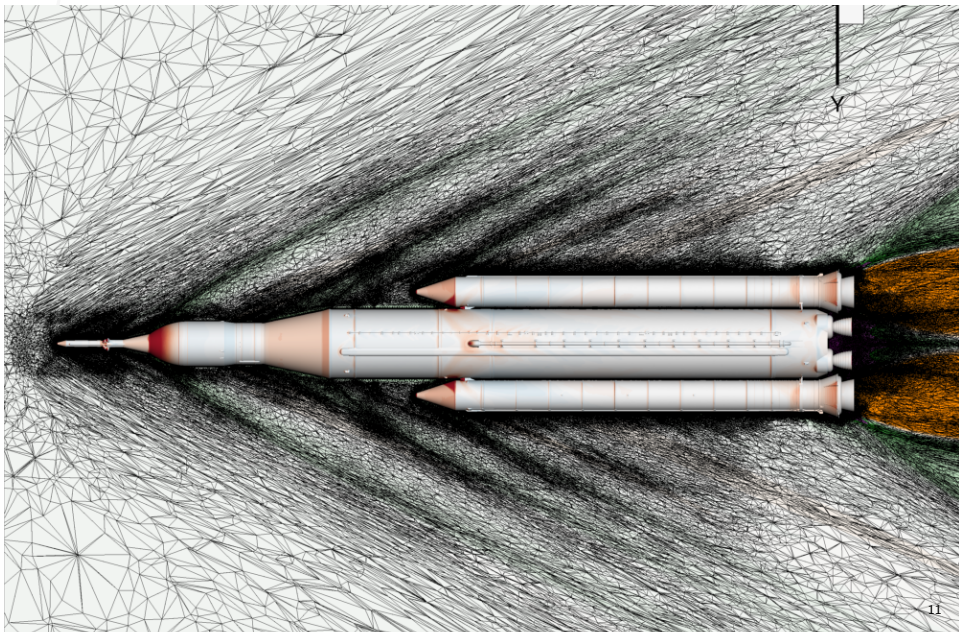
<https://overflow.larc.nasa.gov/>

Cart3D



<https://www.nas.nasa.gov/publications/software/docs/cart3d/>

Tool #4: mesh adaptation





Booster Separation



Motivation

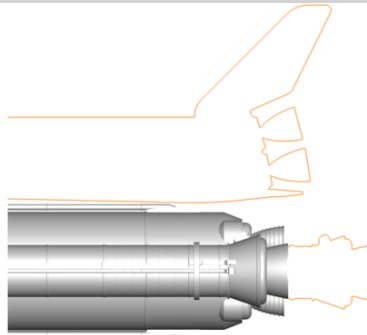
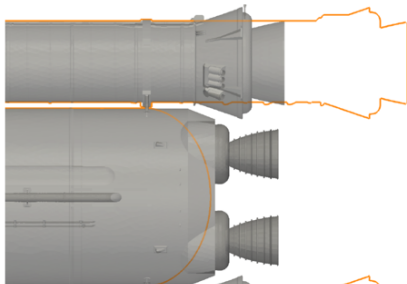


Motivation

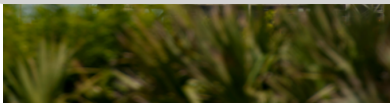
STS



SLS

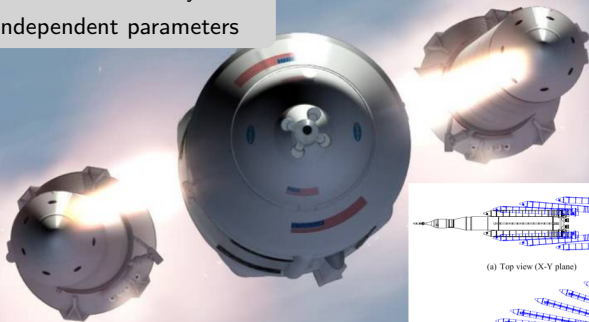


Similar hardware, different environments

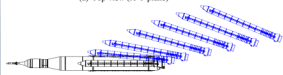


Booster Separation Overview

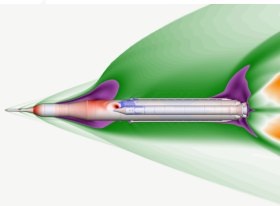
- Occurs at ~ 2 min and Mach ~ 4
- 16 BSMs fire simultaneously
- 33 total independent parameters



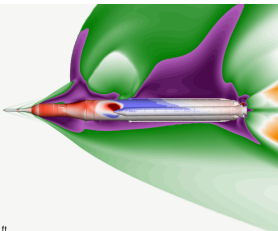
(a) Top view (X-Y plane)



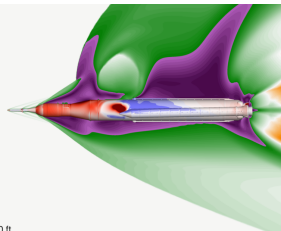
(b) Side view (X-Z plane)



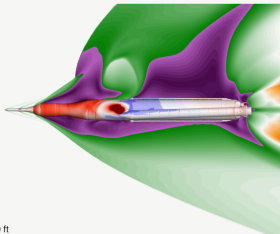
$dx=0.0$ ft



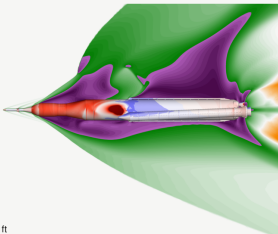
$dx=2.0$ ft



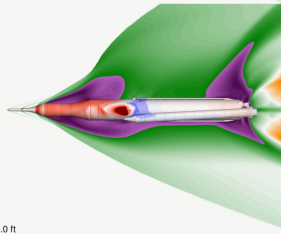
$dx=4.0$ ft



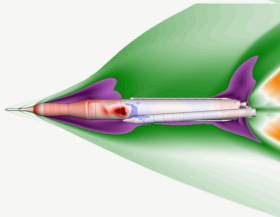
$dx=6.0$ ft



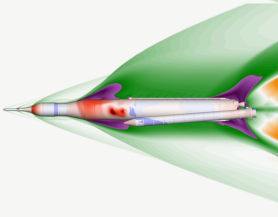
$dx=8.0$ ft



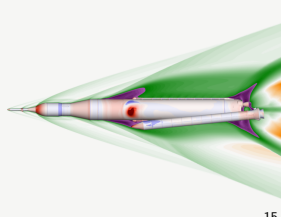
$dx=10.0$ ft



$dx=12.0$ ft



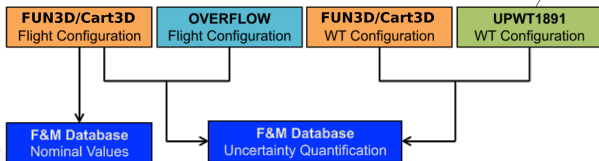
$dx=15.0$ ft



$dx=20.0$ ft

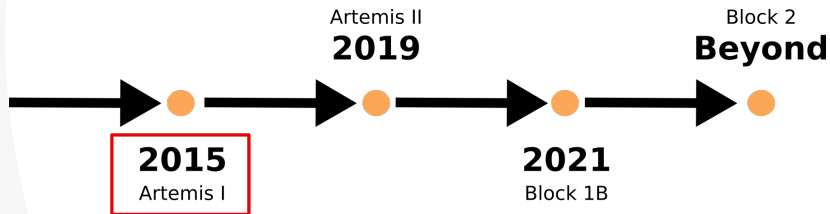
Booster Separation Database

- Shuttle used wind tunnel to build database
- SLS uses CFD for nominals (cost, physics)
- Wind tunnel still used for uncertainty



Forces and moments serve as inputs for GN&C simulations

Booster Separation Timeline



- Cart3D
- Limited to 8 dimensions
- Initial development of CAPE software
- Over 20k cases run

Simplifying the Problem

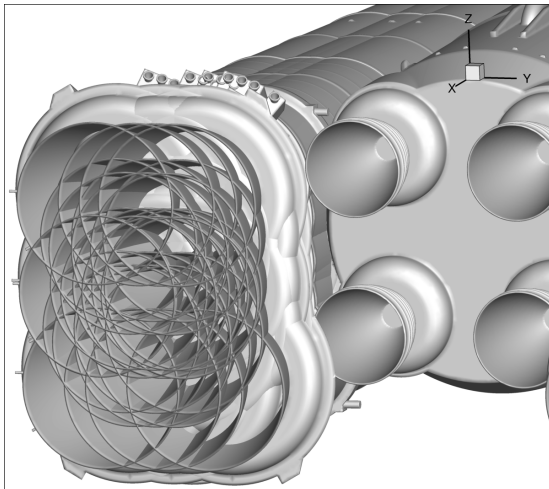
8-dimensional run matrix:

Variable	Description
dx	SRB axial translation
dy	SRB outward translation
dz	SRB vertical translation
$dpsi$	SRB yaw (rel. to core)
$dtheta$	SRB pitch
α	CORE angle of attack
β	CORE sideslip angle
$CTBSM$	BSM thrust coefficient

Other variables held constant:

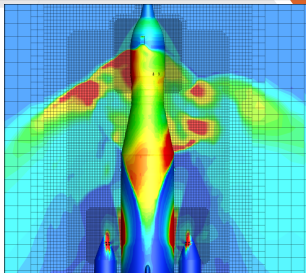
Variable	Description
$dphi$	SRB roll
$mach$	CORE Mach number
$CTCSE$	CORE engine thrust
$CTSRB$	SRB thrust

Full run matrix: $\mathcal{O}(10k)$ cases

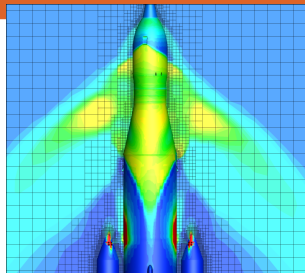


All SRB positions simulated at $dx=6$ ft in Artemis I database

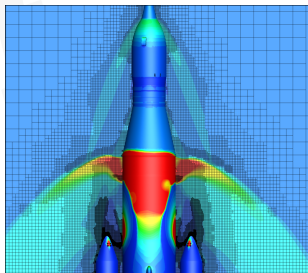
Artemis I B. Separation with Cart3D



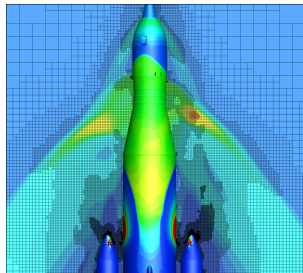
Manually specified mesh



Mesh generated automatically with
autoInputs

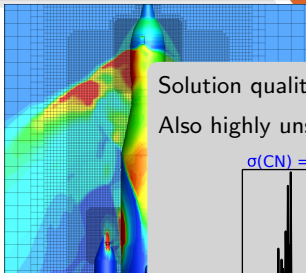


Adapted mesh using 10 cycles from
coarse initial mesh

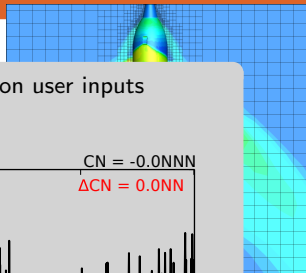
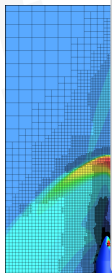


Adapted mesh using 6 cycles from
finer initial mesh

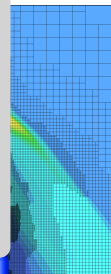
Artemis I B. Separation with Cart3D



Manually specified

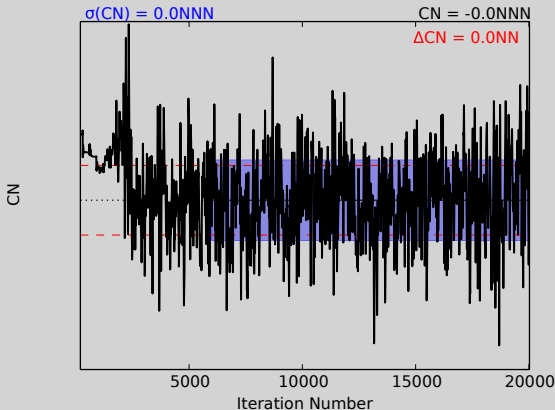


Adapted with



Solution qualitatively dependent on user inputs

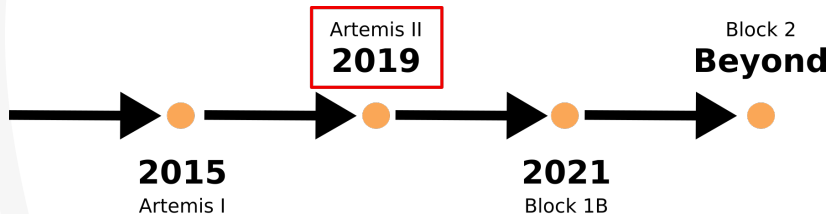
Also highly unsteady:



Adapted mesh using 10 cycles from
coarse initial mesh

Adapted mesh using 6 cycles from
finer initial mesh

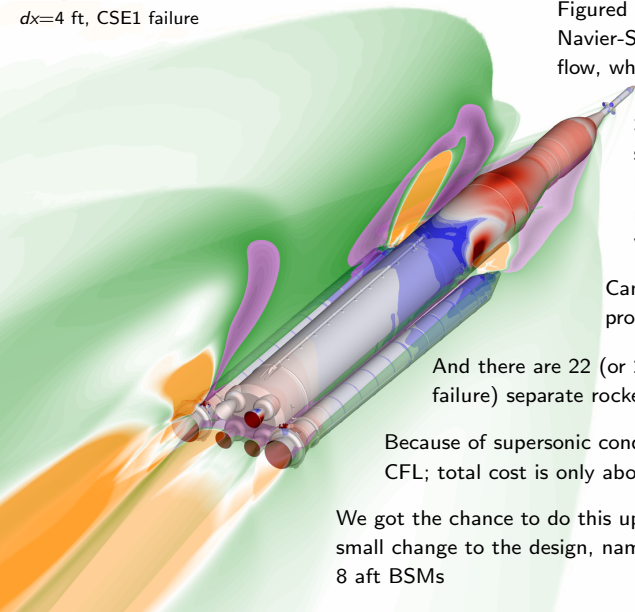
Booster Separation Timeline



- FUN3D
- *Smarter* run matrix
- Expanded variable set (13 dimensions)
- Over 14k CFD cases run

Artemis II B. Separation with FUN3D

Example from relatively normal
 $dx=4$ ft, CSE1 failure



Figured out how to use a full
Navier-Stokes solver (FUN3D) for this
flow, which required some luck

Setup is very complicated; three
separate bodies, which are
rotated and translated into
place. Then create case-specific
volume grids

Can handle slight intersections,
processed before volume grid

And there are 22 (or 21 when modeling an engine
failure) separate rockets firing

Because of supersonic conditions, can use a huge (~ 200)
CFL; total cost is only about 4x what we had from Cart3D

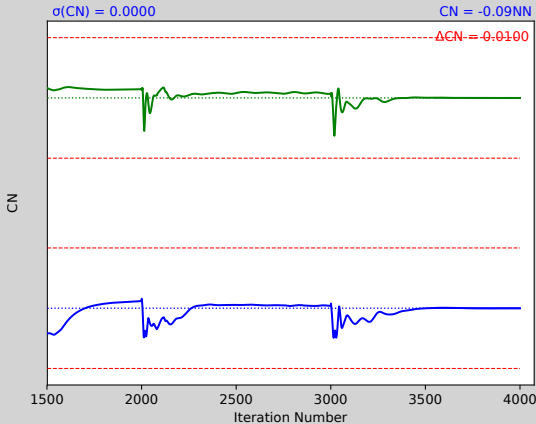
We got the chance to do this update because Artemis II has a
small change to the design, namely a 15° rotation of 6 of the
8 aft BSMs

Artemis II B. Separation with FUN3D

Example from relatively normal
 $dx=4$ ft, CSE1 failure

Solutions now very steady

Showing an example with normal force on both SRBs



Figured out how to use a full

(FUN3D) for this
some luck

complicated; three
s, which are
translated into
create case-specific

intersections,
volume grid

ling an engine

a huge (~200)
had from Cart3D

Artemis II has a

small change to the design, namely a 15° rotation of 6 of the
8 aft BSMs

FUN3D Procedure

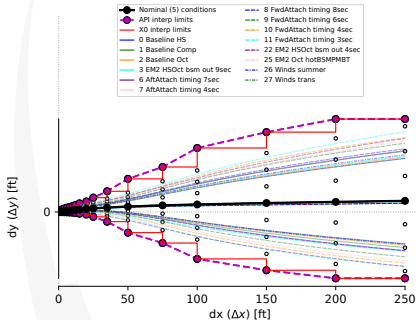
- Despite the complexity of the flow, this is a “computationally easy” problem
- Run FUN3D steady-state and aggressively; CFL ramps up to 200
- Nominally runs 4000 iterations for BSM-on, 3000 for BSM-off

Procedure

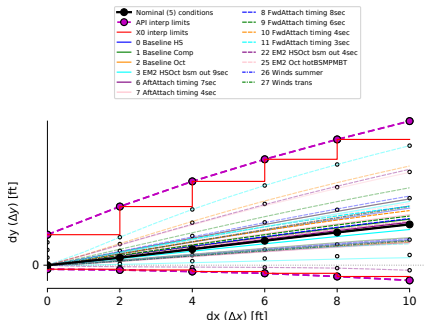
1. Move SRB surfaces into place
2. Run `intersect` and patch up if necessary
3. Generate volume mesh using `aflr3` (use one node)
4. Resubmit job with more than 1 compute node
5. Run first 1000 iterations, then adapt mesh to 19M points
6. Run next 2000 (1000 for BSM-off) iterations, then adapt mesh to 25M points
7. Run last 1000 iterations

- Initial mesh has about 12M points
- Using FUN3D-internal feature-based adaptation
- If mesh fails, we have sequence of AFLR3 settings to try
- If FUN3D fails, we have series of other CFL schedules to try

Artemis II Run Matrix



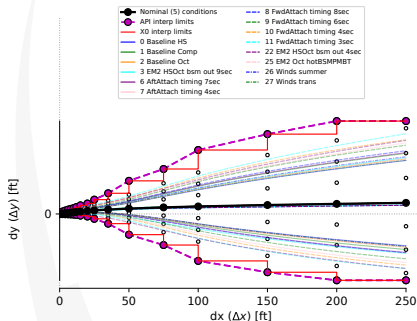
dy run matrix points and trajectory limits vs dx



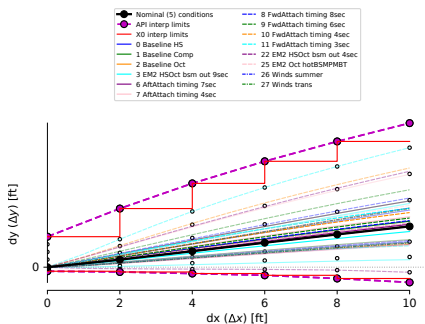
... focus on first 10 ft of dx

- For Artemis I, we had a manual run matrix of just min/mean/max conditions
- CFD for Artemis II was closer to the actual conditions expected in flight

Artemis II Run Matrix



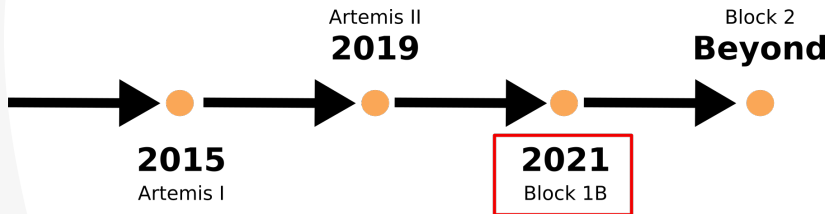
dy run matrix points and trajectory limits vs dx



... focus on first 10 ft of dx

- For Artemis I, we had a manual run matrix of just min/mean/max conditions
- CFD for Artemis II was closer to the actual conditions expected in flight
- Despite all these improvements, UQ was not significantly better than Artemis I

Booster Separation Timeline



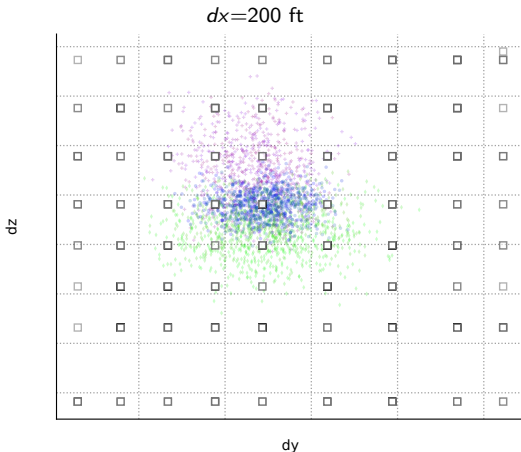
- FUN3D
- Correlated run matrix (covariance)
- Reduced number of variables (lessons learned)
- Similar computational cost to Artemis II, fewer failures

Block 1B: Better Run Matrix

- Plots of SRB dy vs dz
- Run matrix tailored to 13 GN&C scenarios in three families
- dy and dz mostly uncorrelated
- Typical rectangular run matrix appropriate

□ Run Matrix (1002)

- Baseline TD2A
- Baseline TD2B
- Baseline TD2D
- Baseline TD2E
- ◆ TD2A 3-sec Delay
- ◆ TD2E 3-sec Delay
- ◆ TD2E 4-sec Delay
- ◆ TD2E 5-sec Delay
- ◆ TD2E 7-sec Delay
- + TD2A BSM-out
- + TD2B BSM-out
- + TD2D BSM-out
- + TD2E BSM-out

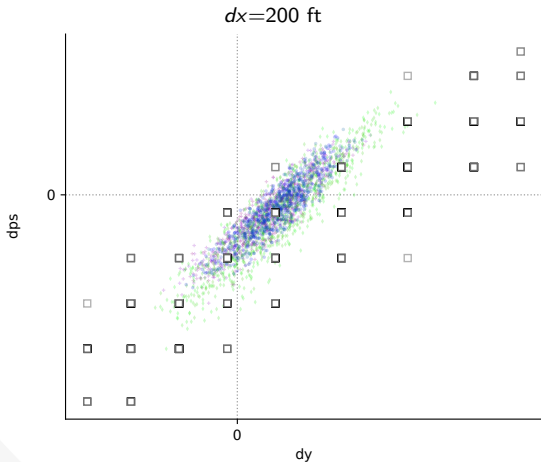


Key Run Matrix Improvements

- Plots of SRB dy vs $dpsi$
- Run matrix tailored to 13 GN&C scenarios in three families
- dy and $dpsi$ highly correlated; higher yaw leads to higher side forces, which push the SRBs to higher dy

□ Run Matrix (1002)

- Baseline TD2A
- Baseline TD2B
- Baseline TD2D
- Baseline TD2E
- ◆ TD2A 3-sec Delay
- ◆ TD2E 3-sec Delay
- ◆ TD2E 4-sec Delay
- ◆ TD2E 5-sec Delay
- ◆ TD2E 7-sec Delay
- + TD2A BSM-out
- + TD2B BSM-out
- + TD2D BSM-out
- + TD2E BSM-out

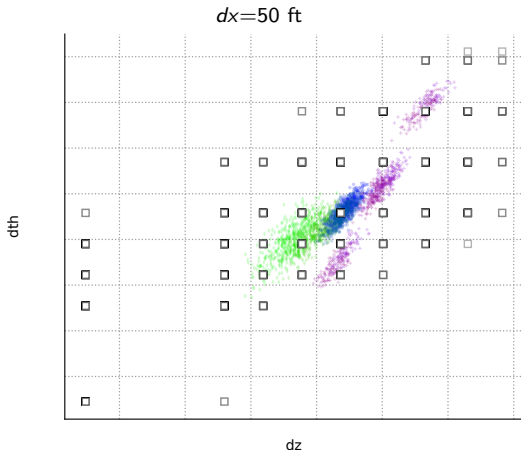


Key Run Matrix Improvements

- Plots of SRB dz vs $d\theta$
- Run matrix tailored to 13 GN&C scenarios in three families
- dz and $d\theta$ highly correlated; more pitch down leads to negative normal forces, which push the SRBs to lower dz

□ Run Matrix (1002)

- Baseline TD2A
- Baseline TD2B
- Baseline TD2D
- Baseline TD2E
- ◆ TD2A 3-sec Delay
- ◆ TD2E 3-sec Delay
- ◆ TD2E 4-sec Delay
- ◆ TD2E 5-sec Delay
- ◆ TD2E 7-sec Delay
- + TD2A BSM-out
- + TD2B BSM-out
- + TD2D BSM-out
- + TD2E BSM-out



Artemis IV booster sep flow

1. Cut plane through $y=0$

Color scheme:

blue: negative $C_p < 0$

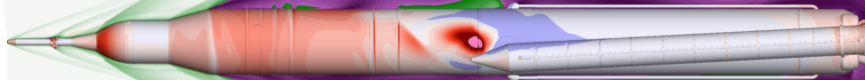
red: positive C_p

pink: very high C_p

purple: $M \leq 1.0$

green: $1 < M < M_\infty$

orange: $M > M_\infty$



Variable	Value
dx	6.0 ft
dy	≈ 2 ft
dz	≈ -7 ft
$d\psi$	$\approx 0^\circ$
$d\theta$	$\approx -3^\circ$
α	$\approx 2^\circ$
β	$\approx -2^\circ$

Artemis IV booster sep flow

2. $y=0$ cut plane with mesh

Color scheme:

blue: negative $C_p < 0$

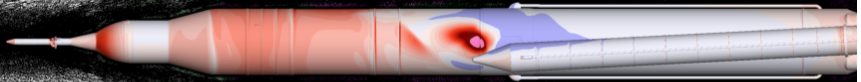
red: positive C_p

pink: very high C_p

purple: $M \leq 1.0$

green: $1 < M < M_\infty$

orange: $M > M_\infty$



Variable	Value
dx	6.0 ft
dy	≈ 2 ft
dz	≈ 7 ft
dps	$\approx 0^\circ$
dth	$\approx 3^\circ$
α	$\approx 2^\circ$
β	$\approx 2^\circ$

Artemis IV booster sep flow

3. $y=0$ cut plane zoom-in

Color scheme:

blue: negative $C_p < 0$

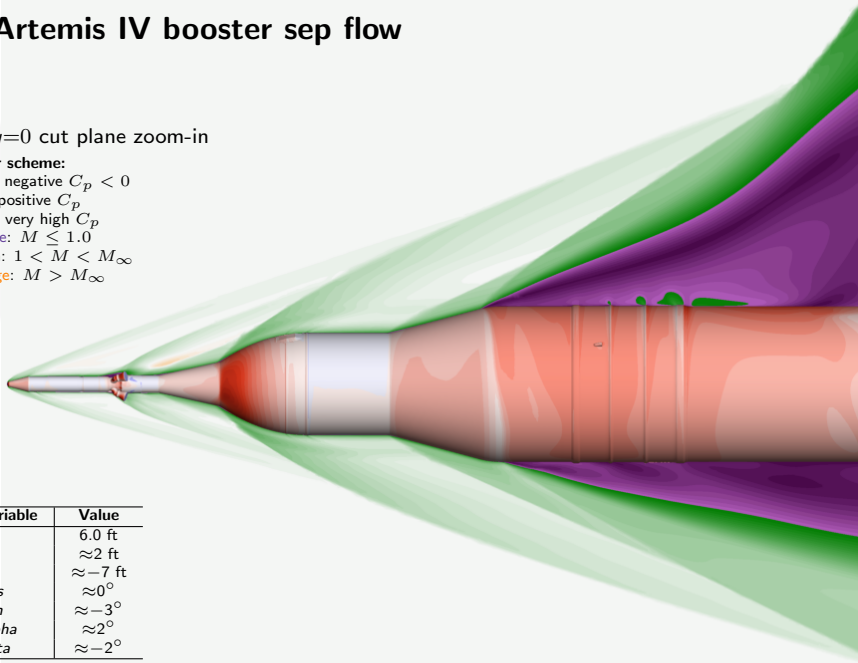
red: positive C_p

pink: very high C_p

purple: $M \leq 1.0$

green: $1 < M < M_\infty$

orange: $M > M_\infty$



Variable	Value
dx	6.0 ft
dy	≈ 2 ft
dz	≈ -7 ft
$d\psi$	$\approx 0^\circ$
$d\theta$	$\approx -3^\circ$
α	$\approx 2^\circ$
β	$\approx -2^\circ$

Artemis IV booster sep flow

4. $z=0$ cut plane

Color scheme:

blue: negative $C_p < 0$

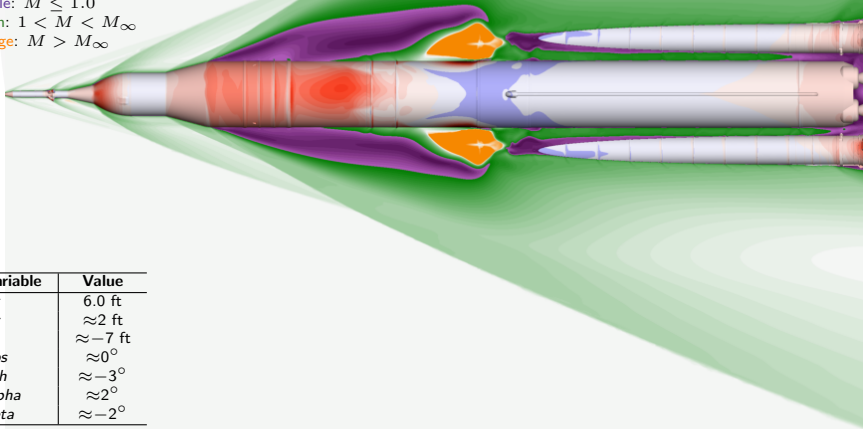
red: positive C_p

pink: very high C_p

purple: $M \leq 1.0$

green: $1 < M < M_\infty$

orange: $M > M_\infty$



Artemis IV booster sep flow

5. Constant- x cut through SRB noses

Color scheme:

blue: negative $C_p < 0$

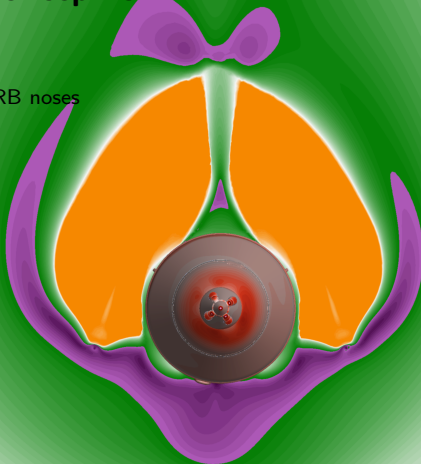
red: positive C_p

pink: very high C_p

purple: $M \leq 1.0$

green: $1 < M < M_\infty$

orange: $M > M_\infty$



Variable	Value
dx	6.0 ft
dy	≈ 2 ft
dz	≈ -7 ft
dps	$\approx 0^\circ$
dth	$\approx -3^\circ$
α	$\approx 2^\circ$
β	$\approx -2^\circ$

Artemis IV booster sep flow

6. Constant- x cut through SRB nozzles

Color scheme:

blue: negative $C_p < 0$

red: positive C_p

pink: very high C_p

purple: $M \leq 1.0$

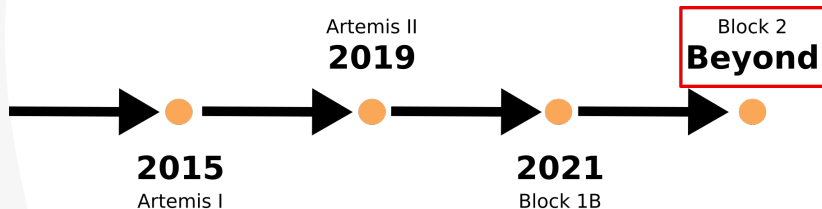
green: $1 < M < M_\infty$

orange: $M > M_\infty$



Variable	Value
dx	6.0 ft
dy	≈ 2 ft
dz	≈ -7 ft
dps	$\approx 0^\circ$
dth	$\approx -3^\circ$
α	$\approx 2^\circ$
β	$\approx -2^\circ$

Booster Separation Timeline

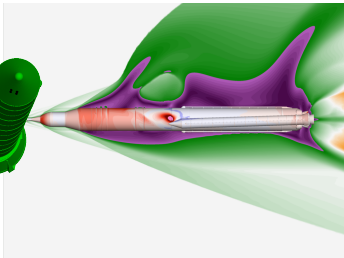
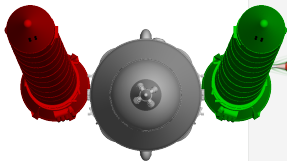


- BOLE - limited supply of SRB sections
- Likely FUN3D
- Tools allow for input on design

Block 2: new & improved design

Block 1B

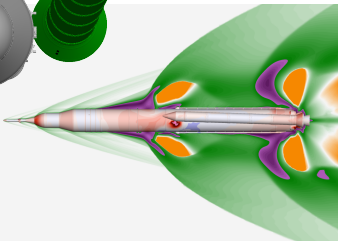
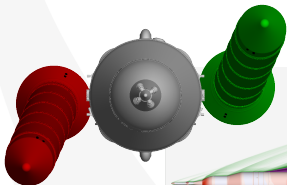
(current design)



- For Block 2, chance to design separation that actually works for SLS
- Block 1 and 1B inherit Space Shuttle design
- Our team ran a handful of FUN3D cases to validate new design in just 2.5 weeks

Block 2

(2030 and beyond)





Artemis I

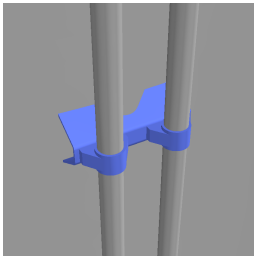


Preparing for Artemis I

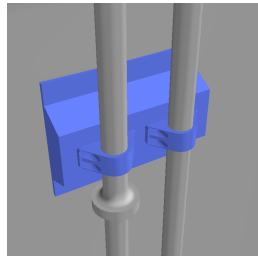
Continuously evaluating updates to the actual geometry as first flight approaches

Most of the aero work for Artemis I is at least 6 years old, so we continuously look for anything that would invalidate our older findings

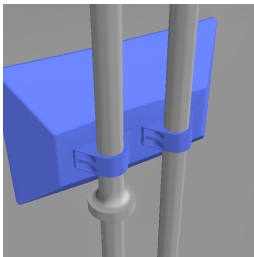
We often run Cart3D on highly detailed geometry, including bolts and things like that, as seen in the SLS-10010 geometry



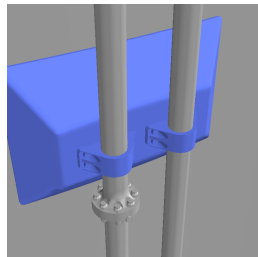
SLS-10005
2014 geometry



SLS-10008// 2016
geometry



SLS-10009
2020 geometry



SLS-10010
2021 geometry

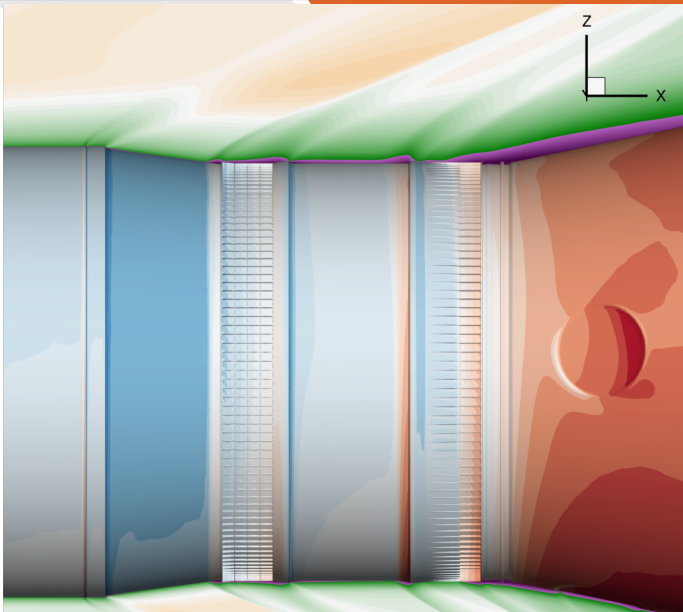
Preparing for Artemis I: ICPS



Artemis II ICPS

<https://www.nasa.gov/exploration/systems/sls/multimedia/images.html>

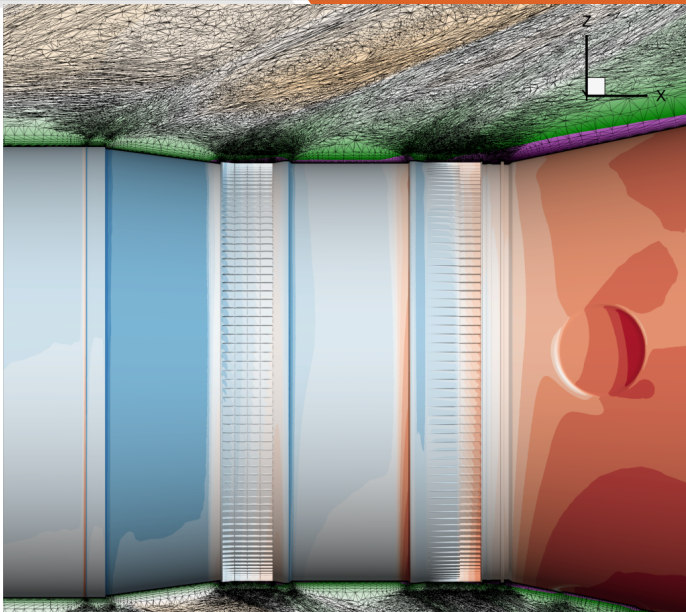
Preparing for Artemis I: ICPS



Continuing to run all our tools on *very* complex geometries

We never stop learning about the SLS flight environment, even if the data from 8 years ago remains valid for engineering purposes

Preparing for Artemis I: ICPS



Continuing to run all our tools on *very* complex geometries

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The Real as-built SLS



If you look closely, some areas of the real vehicle look very . . . different from our models



Acknowledgments

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